Exploiting Monotonicity for Training and Verification of Neural Networks

ПΠ

Technical University of Munich



Background

Neural networks are great at solving many complex tasks, e.g., object detection [10], natural language processing [11], or chess [8]. To ensure the safety of neural networks in safety-critical environments, such as autonomous driving [12], there is a large field of research around the formal verification of neural networks [1]. However, the formal verification of neural networks is computationally hard [5]. Generally, there are two approaches to formally verify neural networks: The first approach encodes the specification and the neural networks as an optimization problem and applies an off-the-shelf solver, e.g., (mixed-integer) linear programming [3] or a satisfiability modulo theories solver [5]; The second approach computes a tight enclosure of the output set of a neural network, e.g., using interval bound propagation [4] or by propagating more expressive set representations like zonotopes [9, 7]. Recent research exploit monotonicity in neural networks to speed-up and improve the formal verification [6].

Description

For monotone functions, exact output bounds can be computed by propagating input bounds. Neural networks can be made monotone by small modification of their architecture; recent research shows promising results by making entire neural networks monotone [6]. However, such monotonic neural networks can only approximate monotone functions. In this thesis, we want to compose multiple monotonic neural networks to approximate arbitrary non-monotonic functions. The composition can be viewed as a mixed-monotone system [2]. Moreover, we want to investigate the performance of compositional monotonic neural networks and find efficient methods to exploit the mixed-monotonic behavior for their formal verification.

Tasks:

- 1. Literature research on formal verification of neural networks.
- 2. Implementation of monotonic neural network architecture and different methods for their composition.
- 3. Training different compositional monotonic neural networks and comparing the performance on monotonic and non-monotonic tasks.
- 4. Development of efficient algorithms for the formal verification of compositional monotonic neural networks.
- 5. Extensive evaluation and comparison with existing approaches for formal verification of neural networks.

References

- Christopher Brix, Mark Niklas Müller, Stanley Bak, Taylor T. Johnson, and Changliu Liu. First three years of the international verification of neural networks competition (VNN-COMP). *Int. Journal on Software Tools for Technology Transfer*, 25(3):329–339, 2023.
- [2] Samuel Coogan and Murat Arcak. Efficient finite abstraction of mixed monotone systems. In Proc. of the Int, Conf. on Hybrid Systems: Computation and Control (HSCC), pages 58–67, 2015.
- [3] Claudio Ferrari, Mark Niklas Müller, Nikola Jovanović, and Martin Vechev. Complete verification via multi-neuron relaxation guided branch-and-bound. In *Proc. of the Int. Conf. on Learning Representations (ICLR)*, 2022.
- [4] Sven Gowal, Krishnamurthy Dvijotham, Robert Stanforth, Rudy Bunel, Chongli Qin, Jonathan Uesato, Relja Arandjelovic, Timothy Arthur Mann, and Pushmeet Kohli. Scalable verified training for provably robust image classification. In *Proc. of the IEEE/CVF Int. Conf. on Computer Vision (ICCV)*, pages 4841–4850, 2019.

Department of Informatics

Chair of Robotics, Artificial Intelligence and Real-time Systems

Supervisor:

Prof. Dr.-Ing. Matthias Althoff

Advisor: Lukas Koller, M.Sc.

Research project: DFG - SPP 2422

Type: BT

Research area: Formal Verification of Neural Networks

Programming language: MATLAB

Required skills: Machine Learning, Formal Methods

Language: English

Date of submission: 16. Dezember 2024

For more information please contact us:

Phone: +49 (89) 289 - 18140 E-Mail: lukas.koller@tum.de Website: ce.cit.tum.de/cps/

- [5] Guy Katz, Clark Barrett, David L. Dill, Kyle Julian, and Mykel J. Kochenderfer. Reluplex: An efficient SMT solver for verifying deep neural networks. In *Int. Conf. on Computer Aided Verification (CAV)*, pages 97–117, 2017.
- [6] Ouail Kitouni, Niklas Nolte, and Mike Williams. Robust and provably monotonic networks. *Machine Learning: Science and Technology*, 4(3), 2023.
- [7] Niklas Kochdumper, Christian Schilling, Matthias Althoff, and Stanley Bak. Open- and closed-loop neural network verification using polynomial zonotopes. In NASA Formal Methods, pages 16–36, 2023.
- [8] David Silver, Thomas Hubert, Julian Schrittwieser, Ioannis Antonoglou, Matthew Lai, Arthur Guez, Marc Lanctot, Laurent Sifre, Dharshan Kumaran, Thore Graepel, et al. A general reinforcement learning algorithm that masters chess, shogi, and go through self-play. *Science*, 362(6419):1140–1144, 2018.
- [9] Gagandeep Singh, Timon Gehr, Matthew Mirman, Markus Püschel, and Martin Vechev. Fast and effective robustness certification. In *Advances in Neural Information Processing Systems (NeurIPS)*, 2018.
- [10] Chien-Yao Wang, Alexey Bochkovskiy, and Hong-Yuan Mark Liao. Yolov7: Trainable bagof-freebies sets new state-of-the-art for real-time object detectors. In *Proc. of the IE-EE/CVF Conf. on Computer Vision and Pattern Recognition (CVPR)*, pages 7464–7475, 2023.
- [11] Tianyu Wu, Shizhu He, Jingping Liu, Siqi Sun, Kang Liu, Qing-Long Han, and Yang Tang. A brief overview of chatgpt: The history, status quo and potential future development. *IEEE/CAA Journal of Automatica Sinica*, 10(5):1122–1136, 2023.
- [12] Cunliang Ye, Yongfu Wang, Yunlong Wang, and Ming Tie. Steering angle prediction yolov5-based end-to-end adaptive neural network control for autonomous vehicles. *Proc.* of the Institution of Mechanical Engineers, Part D: Journal of Automobile Engineering, 236(9):1991–2011, 2022.

ПП

Technical University of Munich



Department of Informatics

Chair of Robotics, Artificial Intelligence and Real-time Systems